DPRG RBNV Chat Record – 9/16/2025

00:01:54.260,00:01:57.260

Mark R: Slight glitch found with Mike accidentally closing the meeting for all.

But we are back!

00:02:59.867,00:03:02.867

Mark R: If anyone has anything they'd like to present, please let me know and i'll add you to the list!

00:50:27.749,00:50:30.749

Ponder SomeMore: maker's pet stls:

00:50:28.530,00:50:31.530

Ponder SomeMore: https://github.com/makerspet/3d_models/tree/main/loki_200mm/stl/

00:52:14.016,00:52:17.016

Ponder SomeMore: "ROS goodness" oxymoron for many

01:12:41.444,01:12:44.444

Ponder SomeMore: https://haraduka.github.io/mevita-hardware/

01:16:21.855,01:16:24.855

Carl Ott: MuJoCo Simulator
https://www.bing.com/ck/a?!&&p=2a747e85a7b6b29da4de9e3043adf94cfa4ceb1b9ee80
b0d24ce343504065e7bJmltdHM9MTc1Nzk4MDgwMA&ptn=3&ver=2&hsh=4&fclid=3aef7fb

f-f84c-6719-21ca-
6c07f91b6696&psq=mujoco+simulation&u=a1aHR0cHM6Ly9naXRodWIuY29tL2dvb2dsZS1kZWVwbWluZC9tdWpvУ28

01:16:38.567,01:16:41.567

Carl Ott: https://github.com/google-deepmind/mujoco

01:18:33.225,01:18:36.225

Carl Ott: https://mujoco.org/

01:19:06.747,01:19:09.747

Carl Ott: MuJoCo Simulation

1

MuJoCo (Multi-Joint dynamics with Contact) is a general-purpose physics engine designed to facilitate research and development in various fields such as robotics, biomechanics, graphics and animation, and machine learning. It provides fast and accurate simulation of articulated structures interacting with their environment.